Matam Santosh

Software Engineer

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PROFESSIONAL SUMMARIES

Software Engineer with 2+ years of experience in Autonomous Vehicles, Embedded Systems, and Automotive Software Development. Expertise in real-time systems, Python-based automation, multithreading, and OTA updates. Proficient in python, AUTOSAR, CAN, NVIDIA GPU, and AWS, ensuring ISO 26262 compliance. Experienced in HIL testing, cloud integration, and diagnostics. Passionate about optimizing vehicle software performance and safety.

WORK EXPERIENCE

Software Engineer

Sep '22 — Present Bengaluru, India

Cognizant

- Developed Python-based real-time control software for LED and steering wheel operations, improving response time by 20%.
 - •Implemented multithreading and concurrency for optimized performance in autonomous vehicle systems.
 - •Designed NVIDIA Conversational AI (LLAMA-3.1-8b-instruct) using Python on AWS EC2 GPU-optimized instances.
 - •Managed OTA system development, including version control, rollback mechanisms, and secure firmware updates.
 - •Developed functional call implementations for model adaptation in automotive applications.
 - •Developed and optimized 3D simulation environments for autonomous vehicle testing using NVIDIA Omniverse, enhancing virtual prototyping and reducing real-world testing costs by 30%.
 - •Developed and automated Python-based HIL test scripts, reducing validation time by 30% and ensuring compliance with ISO 26262 safety standards.
 - •Strong knowledge of AUTOSAR architecture, CAN, HTTP, SNMP protocols, and Linux environments.

EDUCATION

B.Tech in Electronics and Communication Engineering, REVA UNIVERSITY (GPA: 9.32)

Aug '18 — Jul '22 Bengaluru, India

• Bengaluru, India

SKILLS & INTERESTS

Programming Languages: Python, C++, Embedded C

Operating system: RTOS, Windows, Ubuntu

Automotive & Embedded Systems: AUTOSAR, ISO 26262, UART, CAN bus, MQTT, LIN

Cloud & DevOps: AWS, Kubernetes, Docker

Testing & Validation : HIL, Vehicle Diagnostics (OBD-II, UDS)

Tools & Hardware: Visual studio code, JTAG, DSPACE, Git, Control desk, NXP i.MX 8QM, Raspberry Pi, EEPROM

PROJECTS

Software Defined Vehicle project for Accelerator, Cognizant

- Developed Python-based CAN communication system using SocketCAN, reducing latency by 25%.
 - •Implemented OTA workflows for multi-core systems, enabling seamless over-the-air software updates.
 - •Automated cloud-native development workflows for virtualization and software deployment.
 - •Ported software stacks on NXP-Toradex (i.MX 8QM) & Raspberry Pi platforms.

Fiat Ch-Test Automation EEVI, Stellantis

- Developed automated test scripts for Vehicle Functionalities (VF's), CAN/LIN database, and Model Interface Sheet.
 - •Automated test script conversion using Automation Tool Kit (ATK), improving efficiency by 35%.
 - •Executed HIL testing using Automation Desk, resolving critical test failures.
 - •Generated HTML reports and Excel-based test reports for automated test validations.

CERTIFICATIONS